

# High-Speed 3D Sensor with Micrometer Resolution Ready for the Production Floor

Industrial VISION days 2011

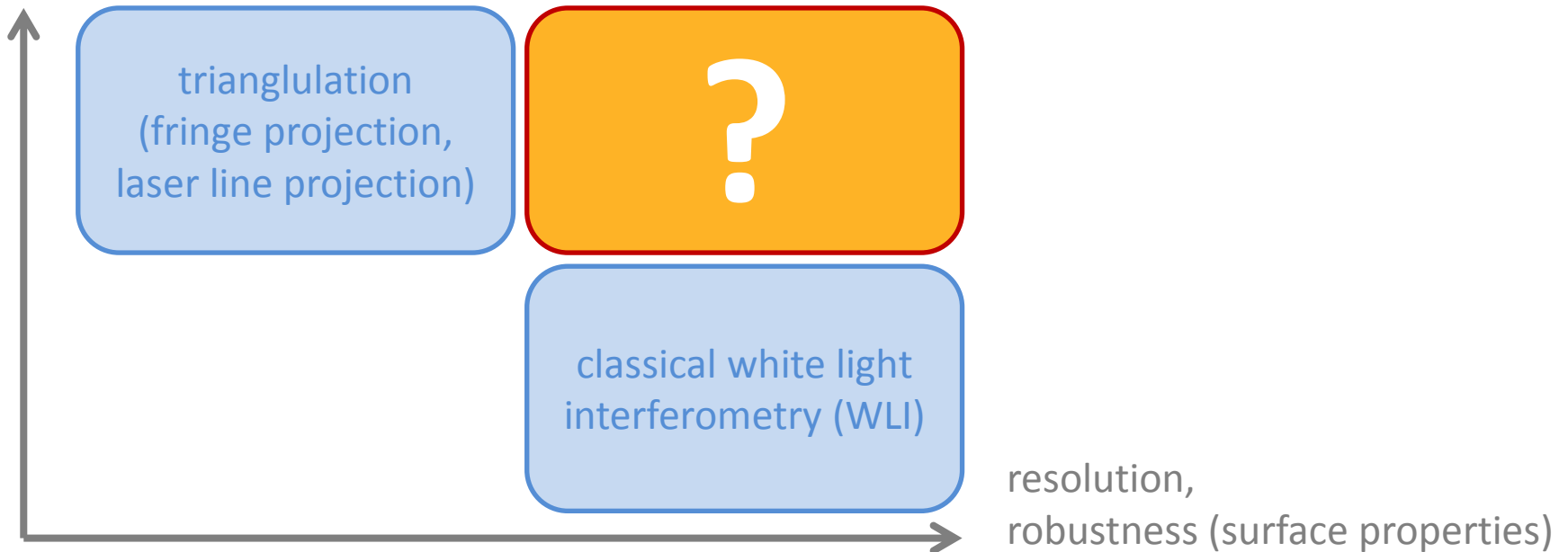
10.11.2011

Christian Lotto

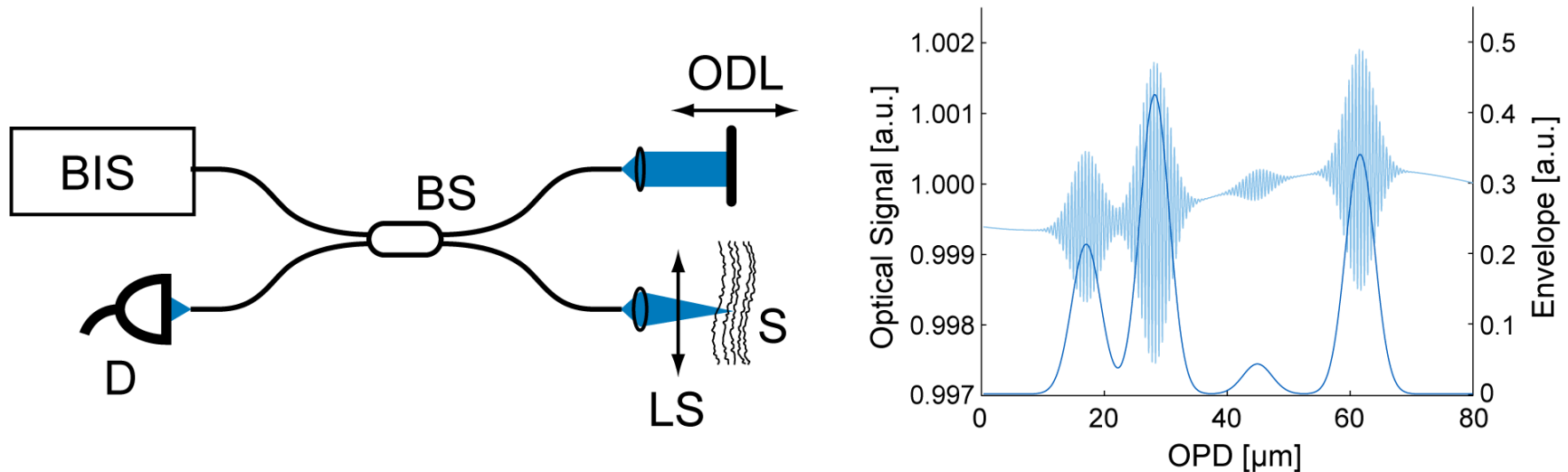


# Challenge: High Precision on the Production Floor

acquisition Speed,  
vibration tolerance



# White Light Interferometry Principle



- Michelson interferometer
- finite temporal coherence / non-zero spectral bandwidth
- path length difference  $<$  coherence length  $\rightarrow$  interference
- parallel measurement via 2D array of pixels

# White Light Interferometry Advantages

- extreme precision
- widest range of surfaces and materials  
(diffusive, reflective, wide range of reflection coefficients)
- wide range of geometries  
(no shadow projection, discontinuous steps)
- tomographic measurement  
(multi surface in non-opaque media)

# Limitations of Conventional White Light Interferometers: Acquisition Speed

## huge amount of data:

- interference signal fringes at light's wavelength period
- vertical sampling at 50-100nm

## data bottleneck:

- inside image sensor of the camera
- transmission from image sensor to camera electronics



best case performance:

scan speed 10-100  $\mu\text{m/s}$ ; 10k surface points/s

# Limitations of Conventional White Light Interferometers: Vibrations

## vibration sensitivity:

- amplitude: fraction of optical wavelength
- frequency: in the range of scan speed/wavelength

low scan speed  $\Rightarrow$  sensitivity in low frequency range

best case: 100Hz-200Hz

$\Rightarrow$  highest precautions, no use on production floor

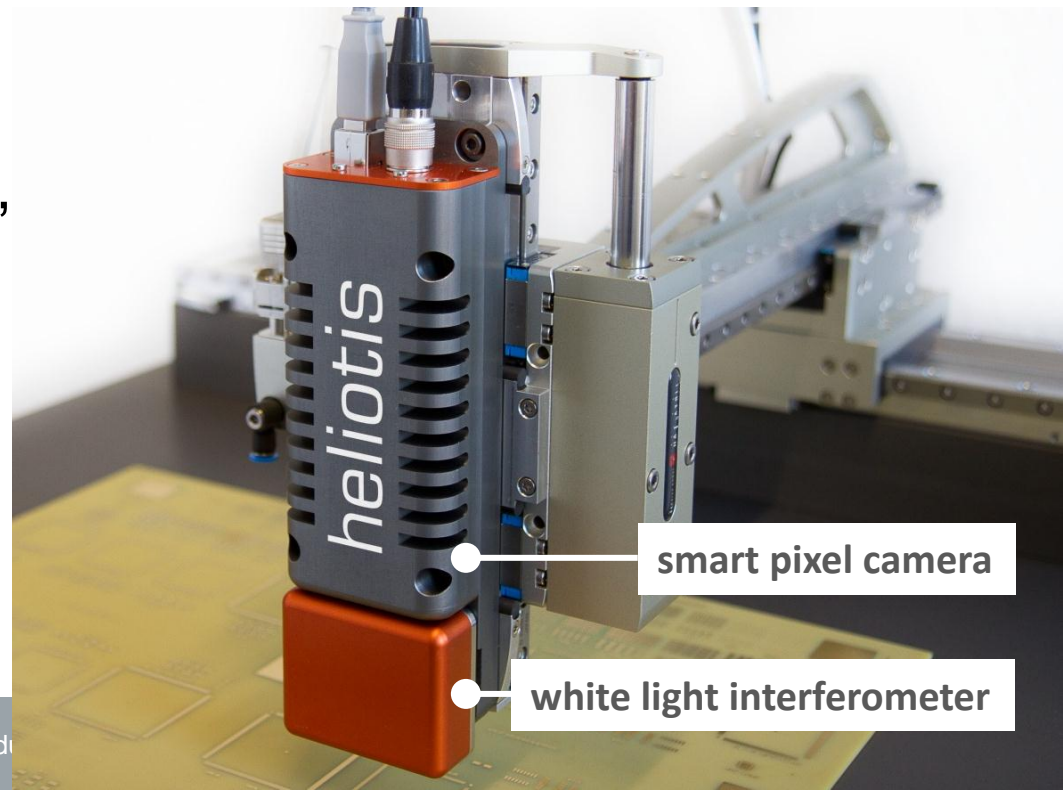
# Heliotis H3 Measurement Module: WLI at Extremely High Speed

## general approach:

- exploit data redundancy
- reduce data amount at earliest possible stage

## implementation:

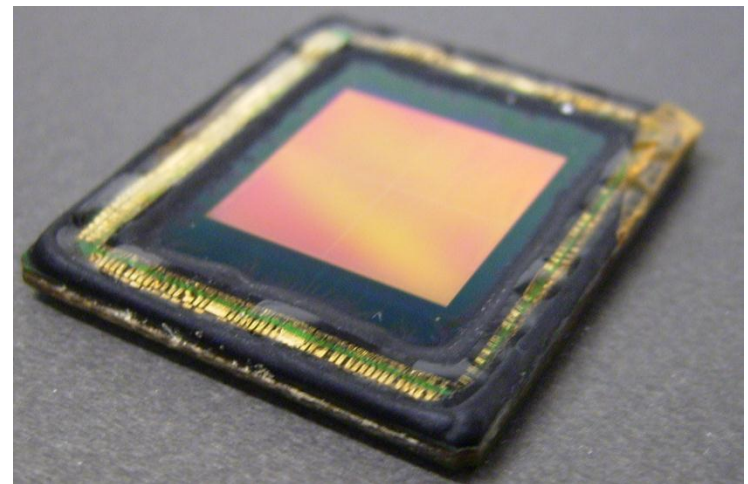
- proprietary “smart-pixel” image sensor



# Heliotis Smart Pixel CMOS Image Sensor

## principal features:

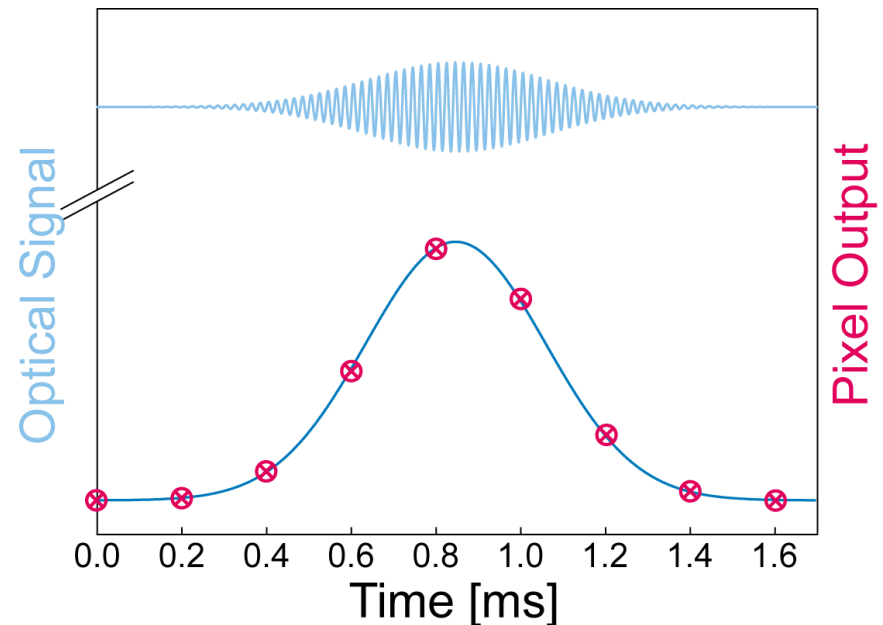
- pixel level suppression of dc component
- pixel level data rate reduction
- very high data output rate  
(5000fps 300x300 pixels/frame)



# Pixel-Level Data Rate Reduction (I)

## data content and redundancy:

- *carrier frequency*:  
no interesting information
- *envelope (amplitude)*:  
surface z-location
- *phase*:  
additional high-resolution  
relative surface z-location  
information

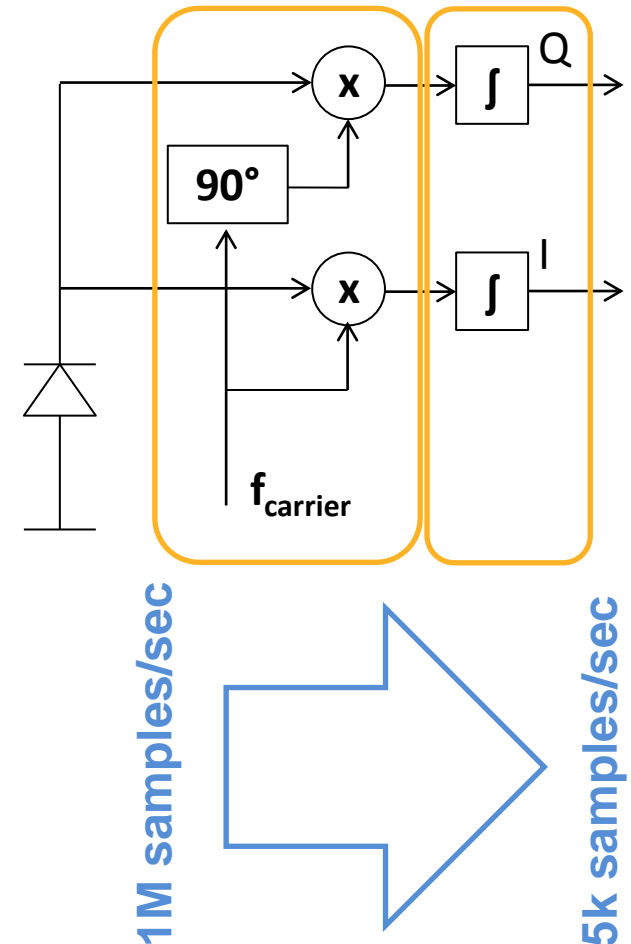


# Pixel-Level Data Rate Reduction (II)

## Functional hardware blocks:

- pixel level envelope extraction
- pixel level low-pass filtering and down-sampling

full quadrature demodulation  
conserves phase information



# Pixel-Level DC Suppression

## challenge:

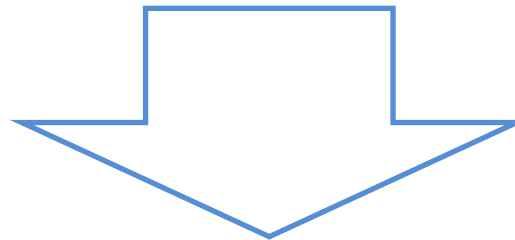
- intra-scene mixture of materials, surface quality and angles → high intra-scene variation of modulation index
- very stringent dynamic range specification

## two-stage pixel-level DC suppression approach :

- coarse swing DC removal from each sample
- fine DC removal by difference computation for demodulation
- overall DC rejection ratio of 60dB

# H3 Acquisition Speed Example

- 300x300 surface points/frame at 25 fps = 2.2 Mpoints/s
- 100 raw volume elements (voxels, envelope samples) per surface point (e.g. 1mm scan range at 1voxel/10 $\mu$ m)
- Interpolation factor = 10 (e.g. 1 $\mu$ m vertical resolution)



220 MVoxels/s (conventional camera would need 22 GS/sec)  
interference signal carrier frequency of 29.4kHz

# H3 Features

- surface topography
- volume tomography
- robust and fast
- sub-micrometer vertical resolution
- modular interferometer optics for scalable lateral resolution (2um to 20um)
- measures any surface
- small form factor
- software modules for rapid integration (windows, mac, linux)
- modular systems of linear motors (portal robots)

# H3 Application Examples:

- in-line quality inspection
- statistical process control
- lab automation
- surface quality (roughness)
- geometrical feature verification
- OEM integration

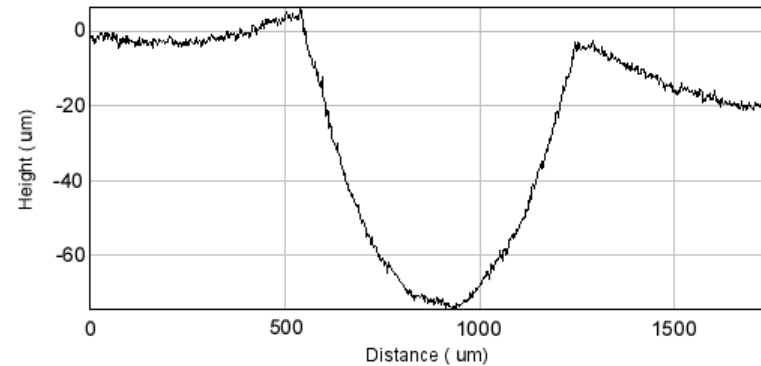
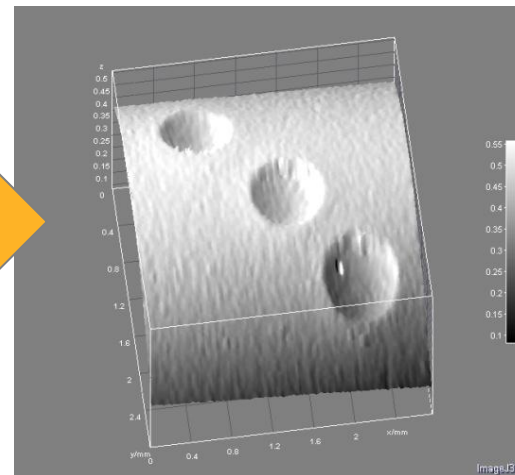
# Defect Analysis (Aerospace)

2D-AOI is used  
to identify potential defects



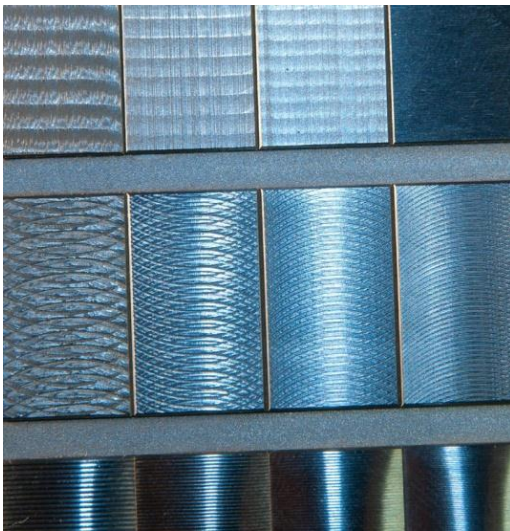
3D

3D-AOI is used  
to characterise defects quantitatively

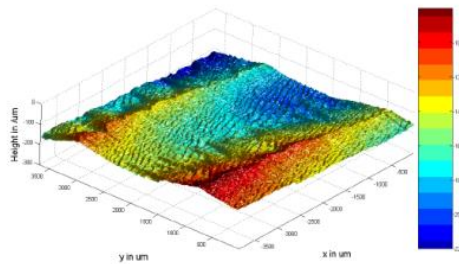
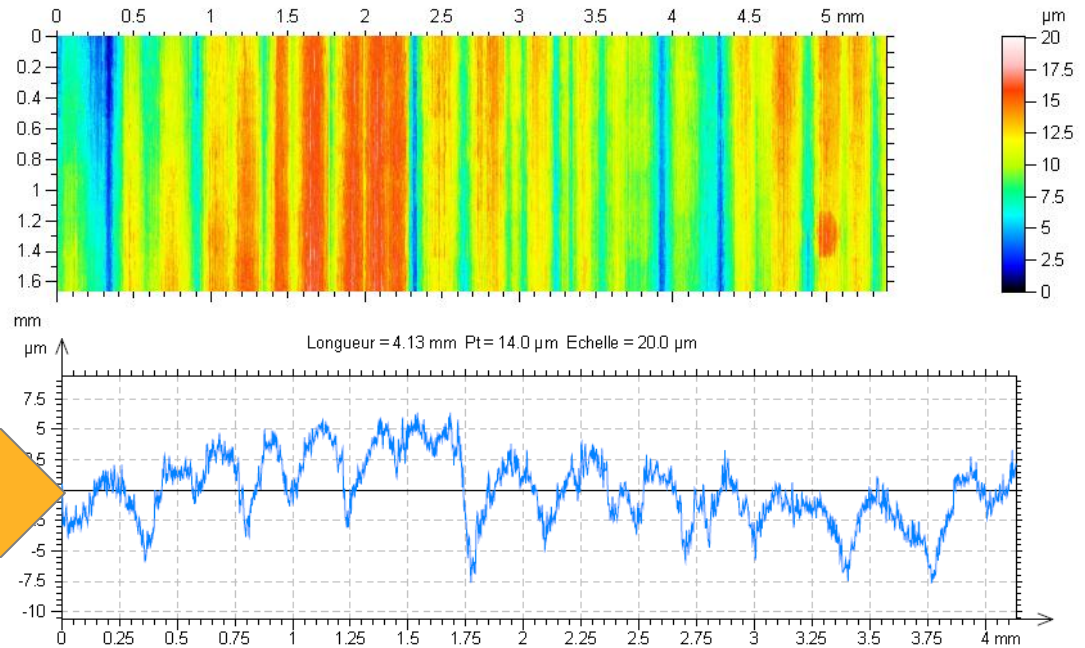


# Surface Characterization (ISO 4287)

2D Image  
of technical surfaces



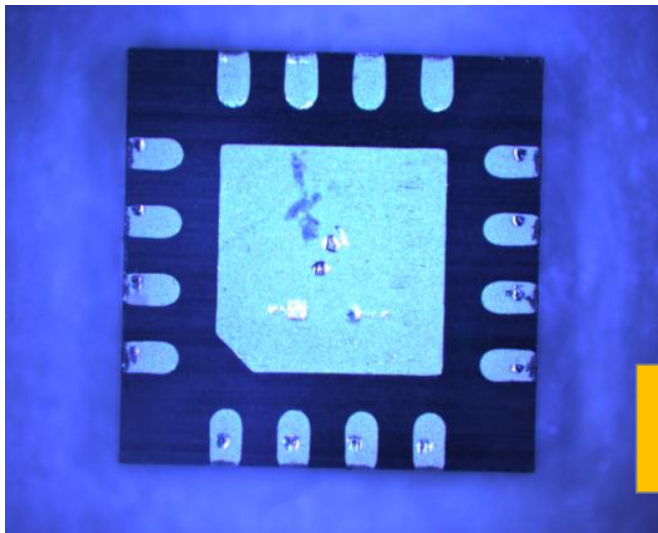
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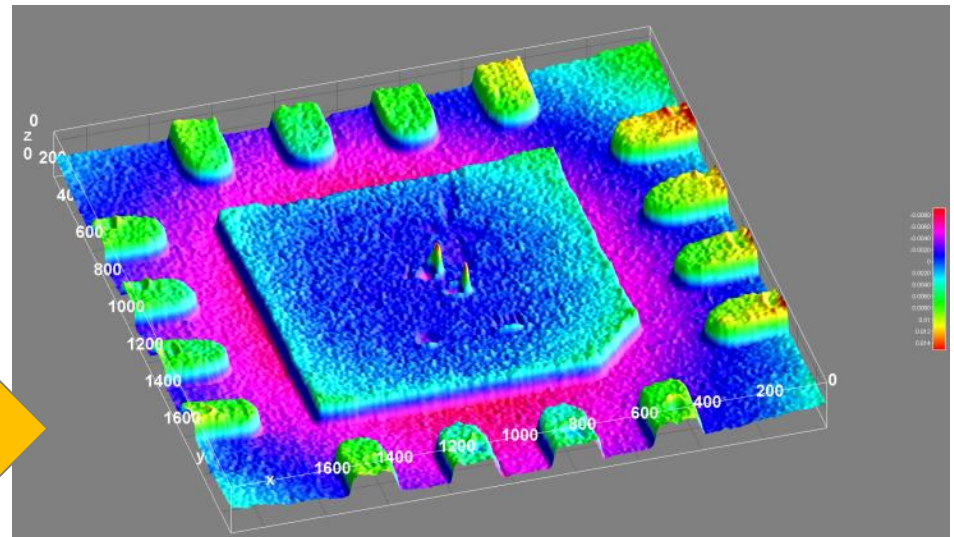
ISO 4287						
		Contexte	Mean	Std dev	Min	Max
Paramètres d'amplitude - Profil de rugosité						
<b>Ra</b>	µm	Fitre gaussien, 0.8 mm	1.56	0.0201	1.50	1.62
<b>Rz</b>	µm	Fitre gaussien, 0.8 mm	9.46	0.253	8.79	10.3
<b>Rt</b>	µm	Fitre gaussien, 0.8 mm	12.5	0.555	10.9	14.2
<b>Rq</b>	µm	Fitre gaussien, 0.8 mm	1.93	0.0206	1.87	1.98

# Electronics: Pads of IC

- highly reflective surfaces
- high dynamic range
- short test cycle times

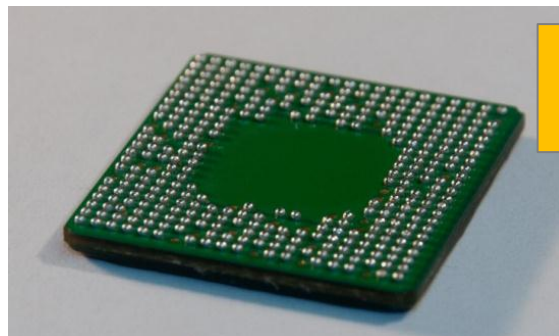


3D

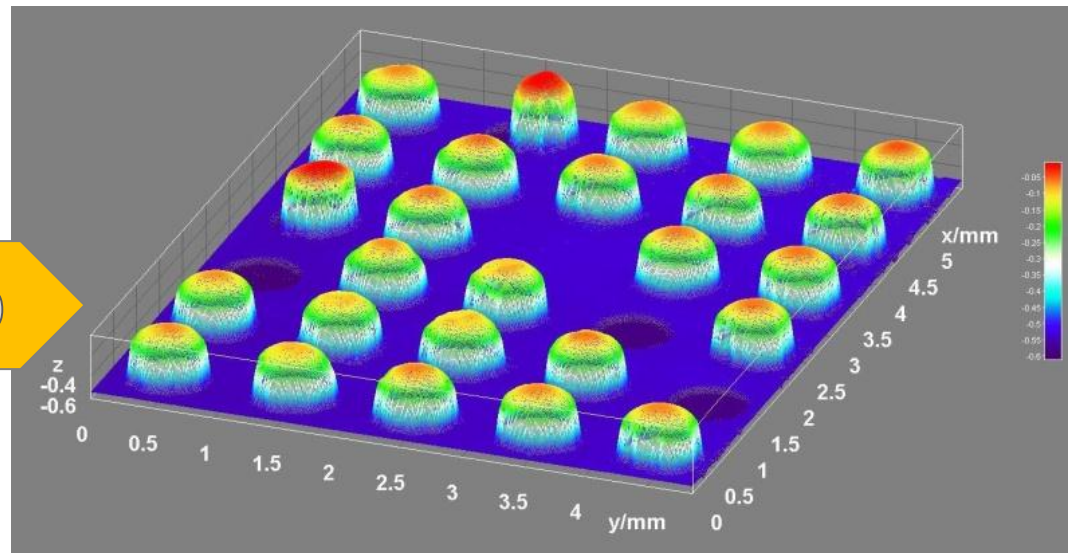


# Electronics (II): Solder Balls (BGA)

- highly reflective surfaces
- high dynamic range
- short test cycle times

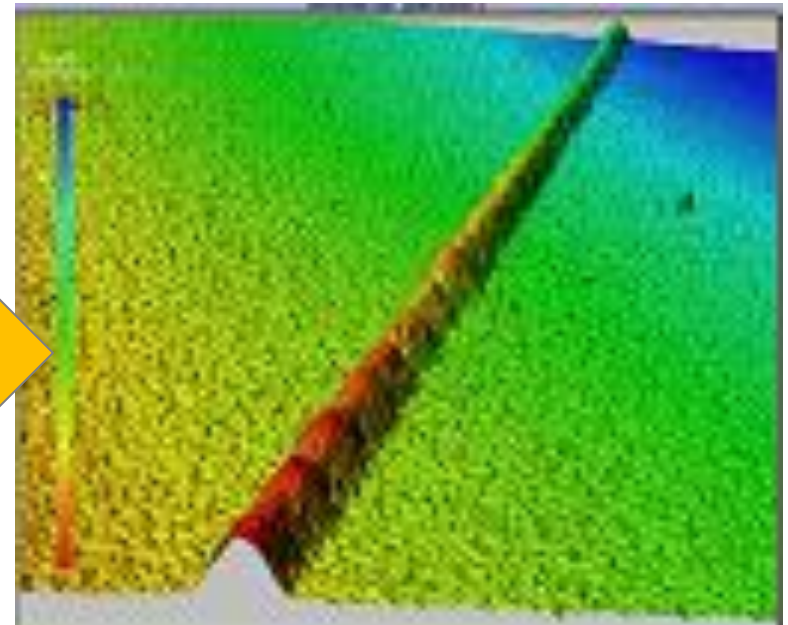
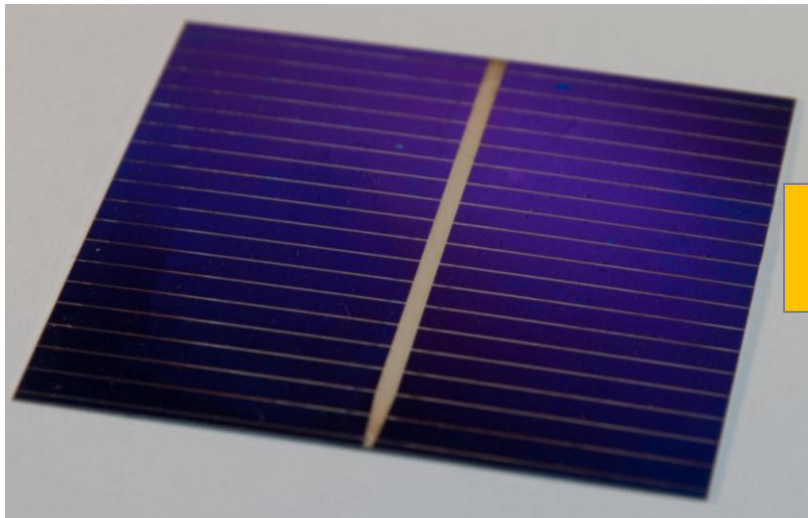


3D



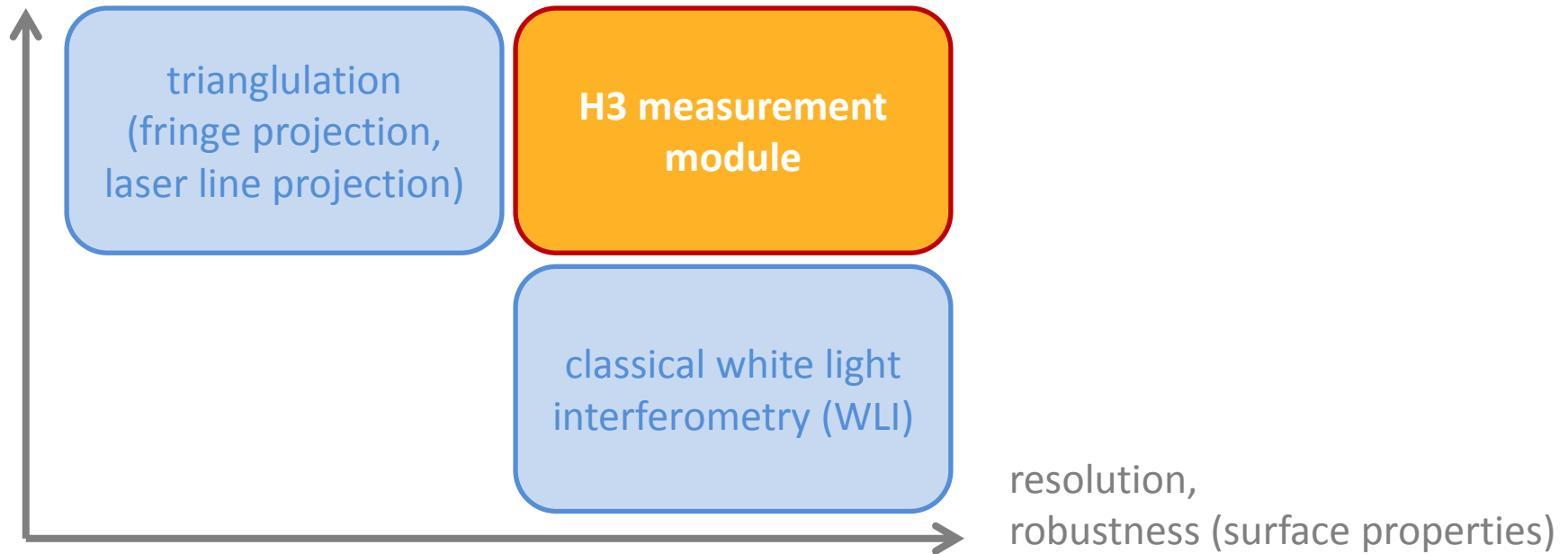
# Electronics (III): Solar Cell Fingers

- highly reflective surfaces
- high dynamic range
- short test cycle times



# Conclusions

acquisition speed,  
vibration tolerance



 **advantages and performance of WLI  
ready for your production floor**

**Thank you for your attention!**